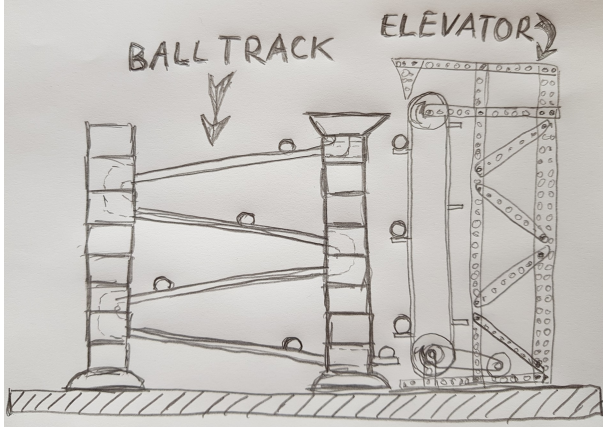


# Automating and Managing an IoT Fleet Using Git

Open Source Summit Europe 2022

Matthias Lüscher, Schindler AG

# About Me

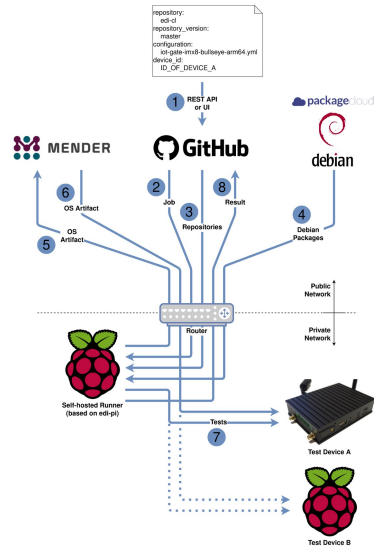


- I prefer to automate boring jobs:
  - E.g. as a child: Operate a ball track using an *elevator*
  - E.g. as a professional: Operate IoT devices that connect *elevators* using CI/CD
- Instead of attending a lot of courses and earning some training awards I decided to create my own open source (automation research) project called [edi](#)
- I live in Switzerland and work for Schindler AG as a principal engineer
- During my spare time I enjoy the nature together with my family (biking, hiking, skiing, ...)
- Contact: [lueschem@gmail.com](mailto:lueschem@gmail.com)

## Mission:

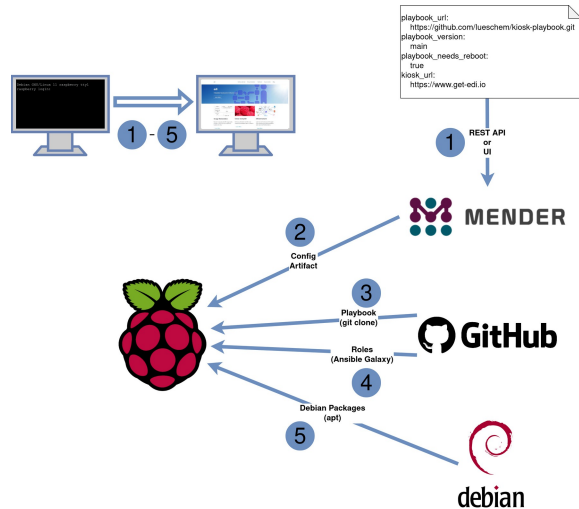
Automate as much as possible in an IoT environment including OS image builds, testing, configuration management and fleet management.

# Agenda



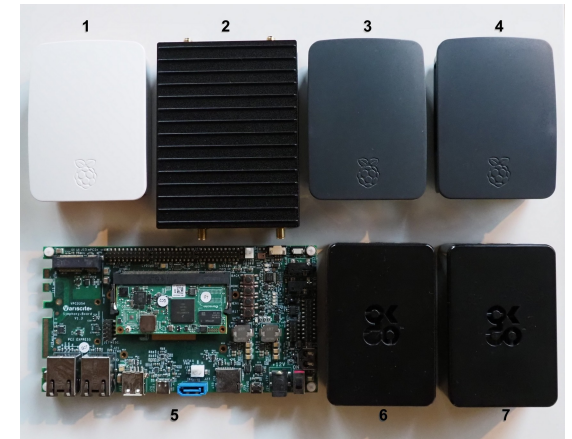
## Continuous Integration

Build an OS image for an IoT device, dispatch it to a device and test it



## Device Management

Adjust an IoT device for an individual use case



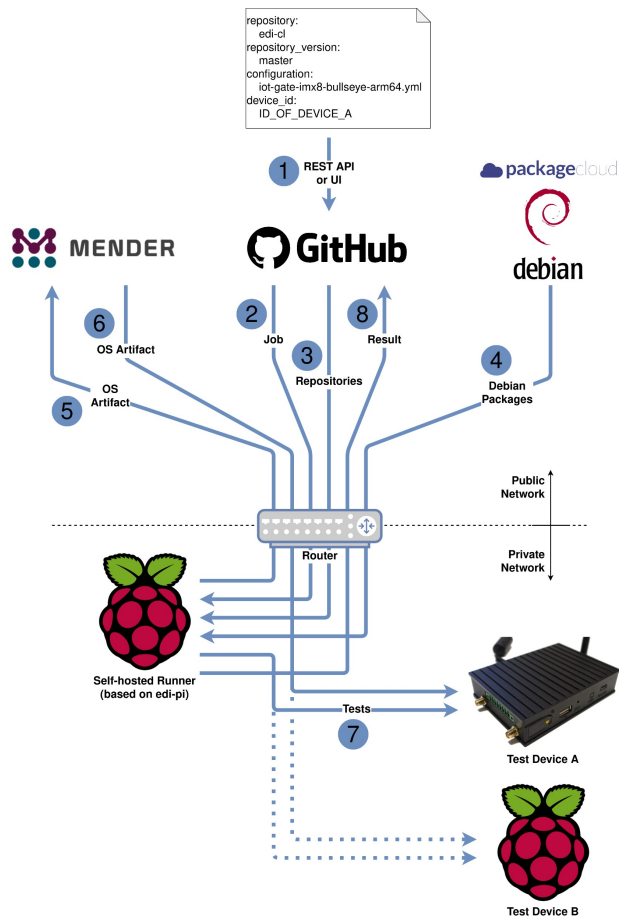
## Continuous Delivery

Keep an entire IoT fleet up to date using git

# Continuous Integration

# Continuous Integration

Overview: OS image → OTA update → test



## Workflow

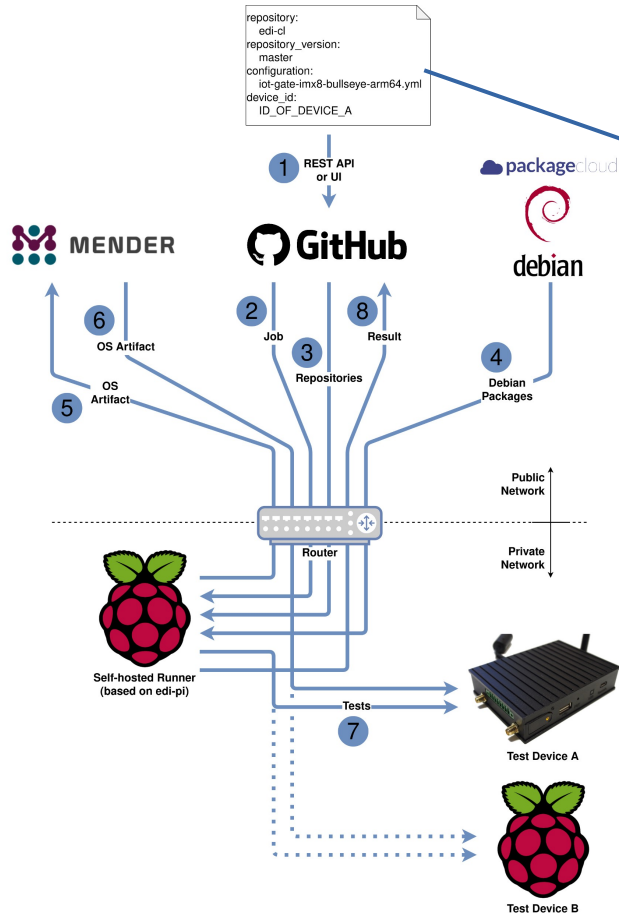
1. Start the workflow on GitHub ([\[1 \(private\)\]](#), [\[1 \(public\)\]](#))
2. A job gets dispatched to the self-hosted runner
3. The runner clones git repositories
4. During the OS build a lot of Debian packages will be fetched
5. The OS artifact will be uploaded to Mender
6. The OS artifact will be dispatched to the chosen device
7. The device will be thoroughly tested ([\[2\]](#))
8. All the build and test results get uploaded to GitHub

## Key Principles

- Security ([\[3\]](#))
- Reproducibility
- Automation
- Quality assurance

# Continuous Integration

## Start workflow



## Workflow

1. Start the workflow on GitHub ([\[1 \(private\)\]](#), [\[1 \(public\)\]](#))
2. A job gets dispatched to the self-hosted runner
3. The runner clones the repository
4. During the OS build, the runner fetches the packagecloud trigger
5. The OS artifact will be pushed to Mender
6. The OS artifact will be pushed to the self-hosted runner
7. The device will be tested
8. All the build and test results are pushed back to the repository

## Key Principles

- Security ([\[3\]](#))
- Reproducibility
- Automation
- Quality assurance

Run workflow

Use workflow from

Branch: main

edi project repository \*

edi-cl

branch/version of edi project repository \*

master

OS image configuration \*

iot-gate-imx8-bullseye-arm64.yml

Mender device ID \*

5ef8c955-4f87-4243-adcd-160f70c3c45e

☒ Test new OS image

Run workflow

# Continuous Integration

## Build the OS image

it starts from scratch...

... using debootstrap!

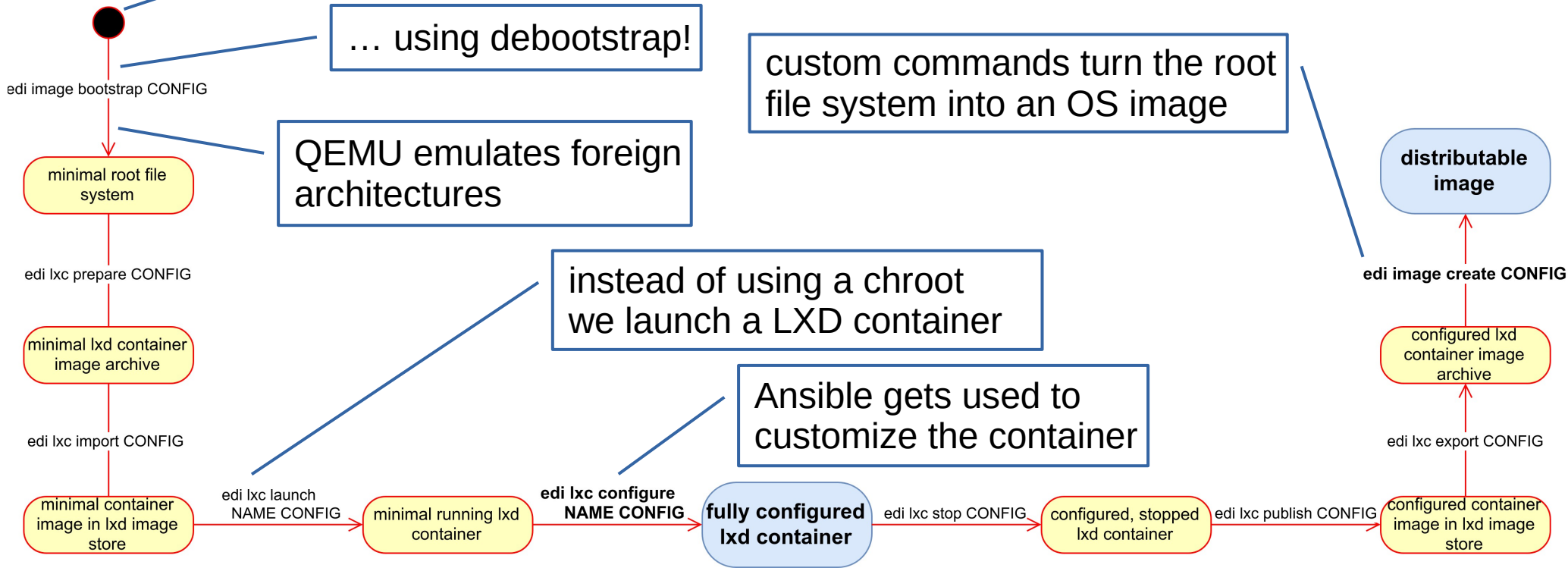
custom commands turn the root file system into an OS image

QEMU emulates foreign architectures

instead of using a chroot we launch a LXD container

Ansible gets used to customize the container

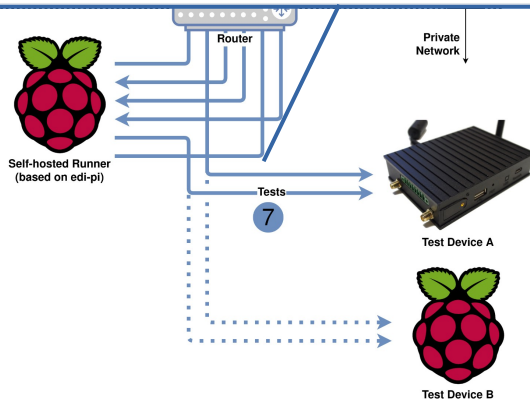
distributable image



# Continuous Integration

## Test the device

```
1 import re
2 import pytest
3
4
5 def test_root_device(host):
6     cmd = host.run("df / --output=pcent")
7     assert cmd.rc == 0
8     match = re.search(r"\d{1,3}%", cmd.stdout)
9     assert match
10    # if the usage is below 50% then the root device got properly resized
11    assert int(match.group(1)) < 50
12
13
14 def test_resize_completion(host):
15     assert host.file("/etc/edi-resize-rootfs.done").exists
16
17
18 @pytest.mark.parametrize("mountpoint", ["/", "/data", "/boot/firmware", ])
19 def test_mountpoints(host, mountpoint):
20     assert host.mount_point(mountpoint).exists
```



## Workflow

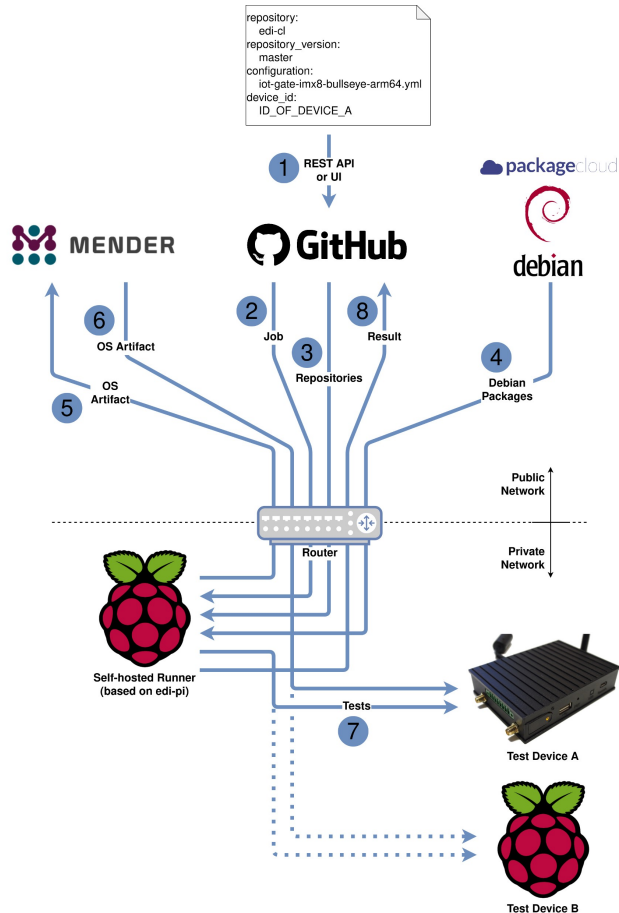
1. Start the workflow on GitHub ([\[1 \(private\)\]](#), [\[1 \(public\)\]](#))
2. A job gets dispatched to the self-hosted runner
3. The runner clones git repositories
4. During the OS build a lot of Debian packages will be fetched
5. The OS artifact will be uploaded to Mender
6. The OS artifact will be dispatched to the chosen device
7. The device will be thoroughly tested ([\[2\]](#))
8. All the build and test results get uploaded to GitHub

## Key Principles

- Security ([\[3\]](#))
- Reproducibility
- Automation
- Quality assurance

# Continuous Integration

## Handling of secret stuff



### Actions secrets

New repository secret

Secrets are environment variables that are **encrypted**. Anyone with **collaborator** access to this repository can use these secrets for Actions.

Secrets are not passed to workflows that are triggered by a pull request from a fork. [Learn more](#).

CI_CD_SSH_PUB_KEY	Updated on 8 Apr	Update	Remove
DEVICE_SECRETS	Updated on 8 May	Update	Remove
MENDER_PASSWORD	Updated on 8 Apr	Update	Remove
MENDER_TENANT_TOKEN	Updated on 8 Apr	Update	Remove
MENDER_USER	Updated on 8 Apr	Update	Remove

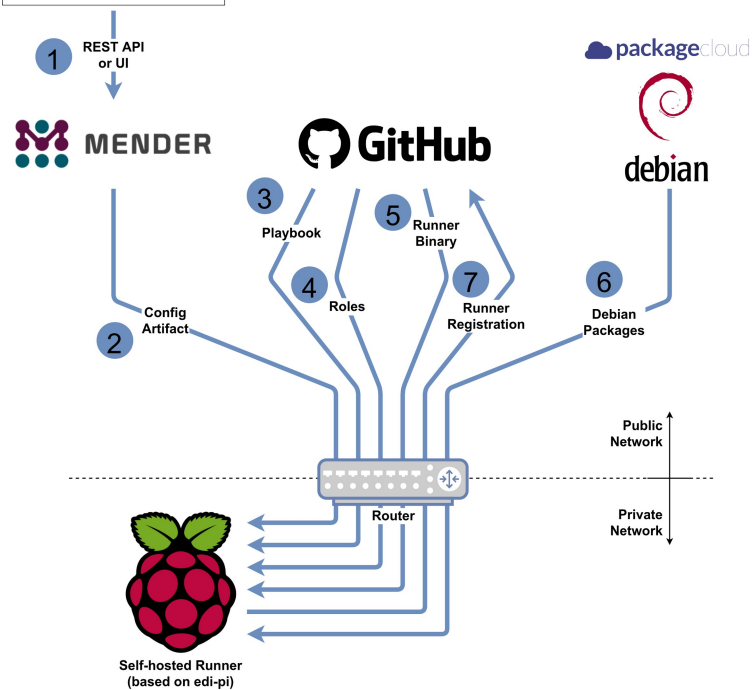
- Security ([3])
- Reproducibility
- Automation
- Quality assurance

# Device Management

# Device Management

## Example: Turn an IoT device into a GitHub runner

```
playbook_url:
  https://github.com/lueschem/
  edi-gh-actions-runner-playbook.git
playbook_version:
  main
github_account:
  lueschem
github_repo:
  edi-ci
access_token:
  ghp_XXXX
```



### Workflow

1. Assign a configuration to a device
2. A configuration artifact gets dispatched to the device
3. The device fetches a playbook using git ([\[1\]](#))
4. The device fetches the roles that the playbook requests
5. The device fetches the .NET GitHub actions runner binary
6. The device fetches some additional Debian packages
7. The GitHub actions runner registers itself on GitHub ([\[2\]](#))

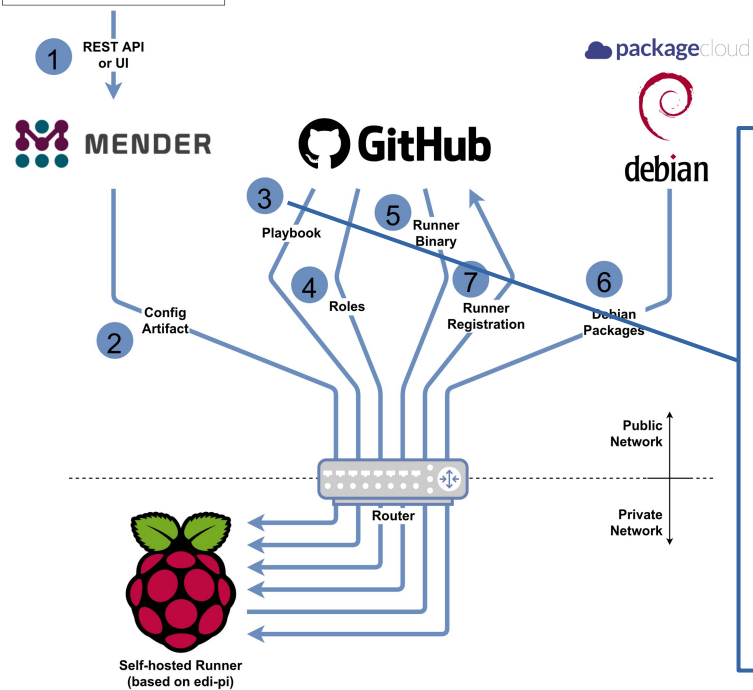
### Key Principles

- Idempotency
- Traceability
- The device knows a lot about itself
- Security
- Reproducibility
- Automation

# Device Management

## Example: Turn an IoT device into a GitHub runner

```
playbook_url:
  https://github.com/lueschem/
  edi-gh-actions-runner-playbook.git
playbook_version:
  main
github_account:
  lueschem
github_repo:
  edi-ci
access_token:
  ghp_XXXX
```



### Workflow

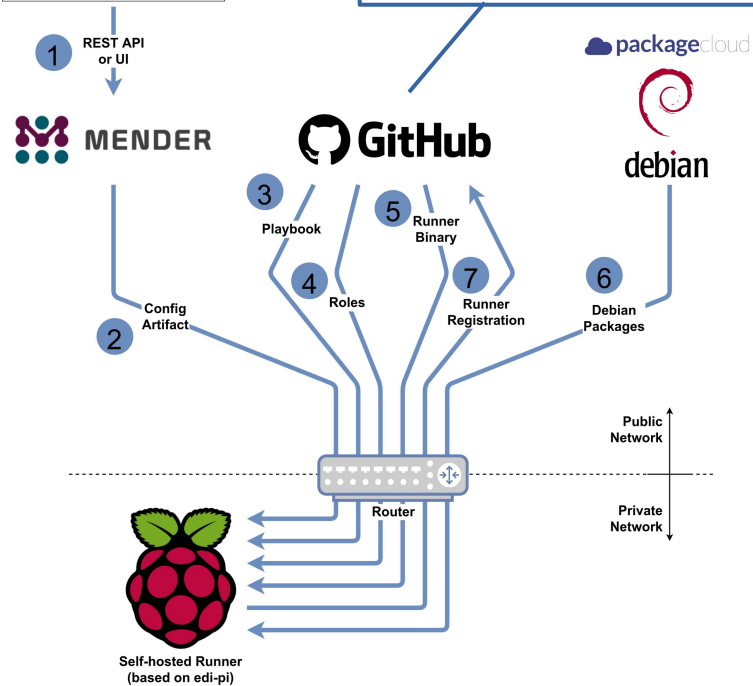
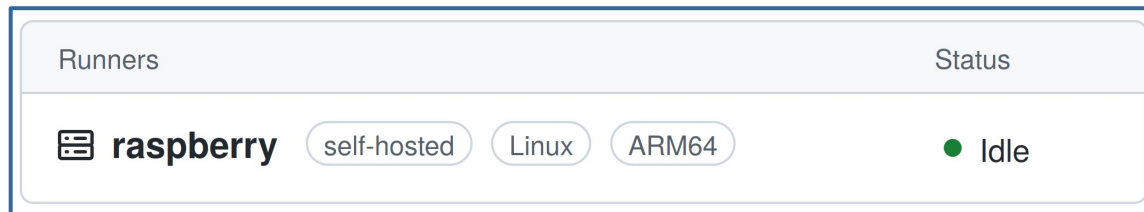
1. Assign a configuration to a device
2. A configuration artifact gets dispatched to the device
3. The device fetches a playbook using git ([1])
4. The device fetches the roles that the playbook requests
5. The device fetches the .NET GitHub actions runner binary

```
1 ---
2 - name: Install GitHub Actions Runner
3   hosts: all
4
5   roles:
6     - role: ansible-github_actions_runner
7       user: gitops
8       become: true
9   - role: edi_installer
10     become: true
```

# Device Management

## Example: Turn an IoT device into a GitHub runner

```
playbook_url:
  https://github.com/lueschem/
  edi-gh-actions-runner-playbook.git
playbook_version:
  main
github_account:
  lueschem
github_repo:
  edi-ci
access_token:
  ghp_XXXX
```



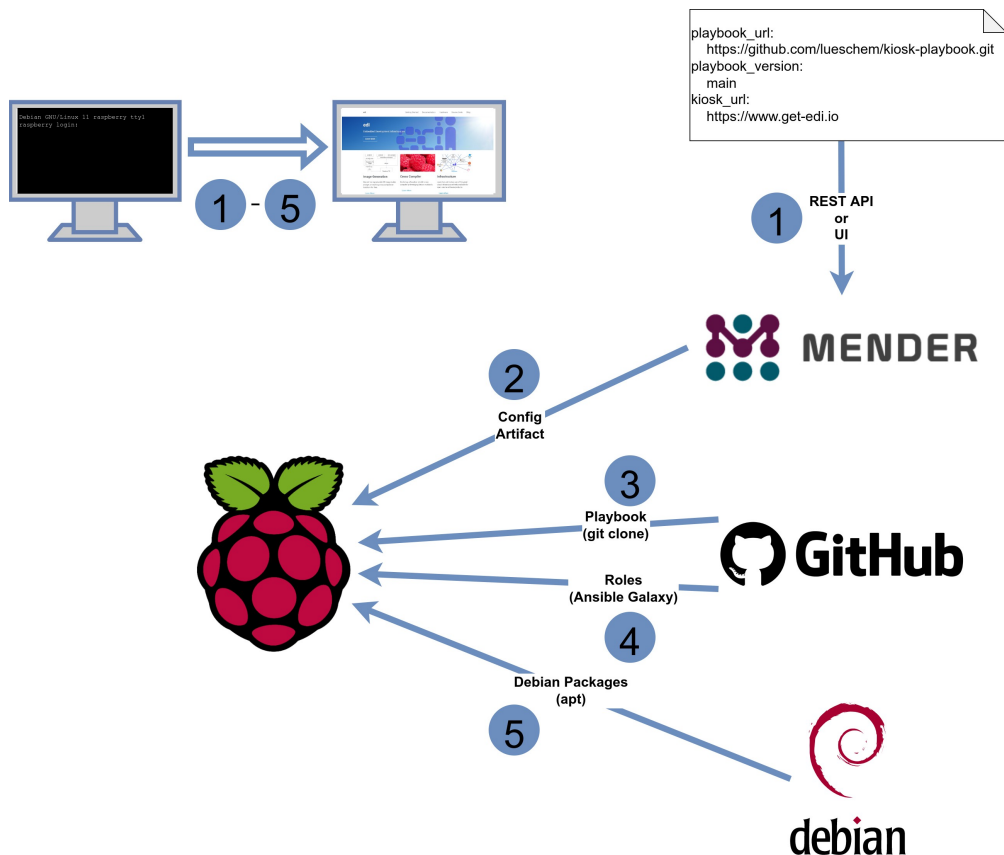
1. The device fetches the playbook using git ([1])
2. The device fetches the roles that the playbook requests
3. The device fetches the .NET GitHub actions runner binary
4. The device fetches some additional Debian packages
5. The GitHub actions runner registers itself on GitHub ([2])

### Key Principles

- Idempotency
- Traceability
- The device knows a lot about itself
- Security
- Reproducibility
- Automation

# Device Management

Example: Turn a headless device into a kiosk terminal



## Workflow

1. Assign a configuration to a device
2. A configuration artifact gets dispatched to the device
3. The device fetches a playbook using git
4. The device fetches the roles that the playbook requests
5. The playbook gets applied and during that process some additional packages might get installed

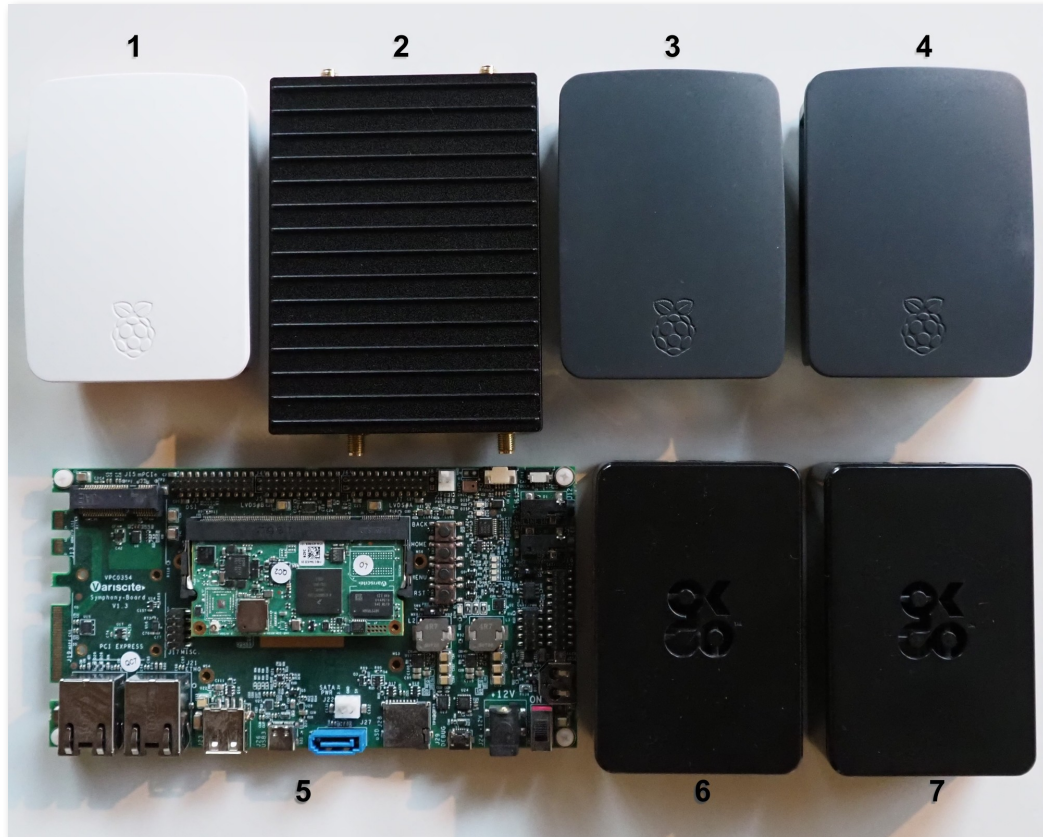
## Key Principles

- Idempotency
- Traceability
- The device knows a lot about itself

# Continuous Delivery

# Demo Fleet

Different devices, different use cases



1. [Raspberry Pi 2](#)  
legacy device
2. [Compulab IOT-GATE-iMX8](#)  
WiFi 6 hotspot
3. [Raspberry Pi 3](#)  
kiosk terminal
4. [Raspberry Pi 3](#)  
kiosk terminal
5. [Variscite VAR-SOM-MX8M-NANO](#)  
development device
6. [Raspberry Pi 4](#)  
GitHub actions runner
7. [Raspberry Pi 4](#)  
kiosk terminal

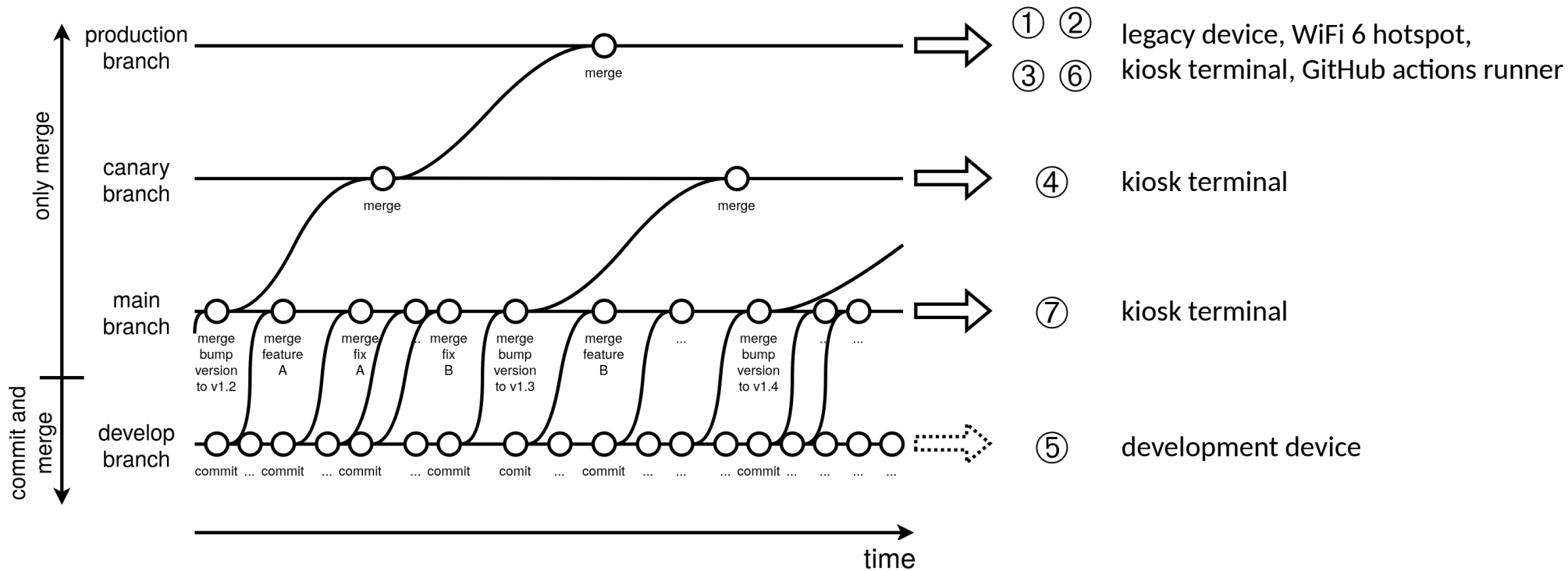
# GitOps

## What is GitOps?

- A new concept/buzzword in the IT industry
  - The goal is to automate as many IT operations as possible
  - The automation shall be based on a fully declared and versioned target state
  - Git is usually the tool of choice to store the target state
  - A bunch of tools are responsible for applying the target state to the infrastructure
- GitOps is not only applicable within the IT industry -  
it can also be very beneficial for embedded and IoT use cases!

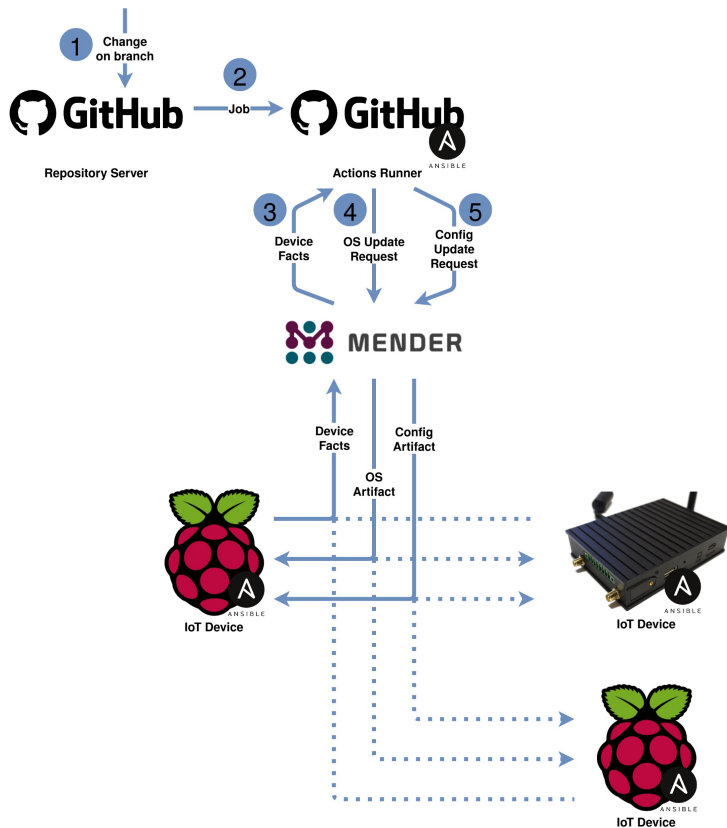
# GitOps

## Map the fleet to a git repository



# GitOps

## How it works behind the scene



### Workflow

1. A branch gets modified:  
develop/feature branch: commit  
main/canary/production branch: merge
2. GitHub dispatches a job to a runner ([1])  
and the runner clones the fleet repository ([2], [3], [4])
3. The fleet facts get retrieved from Mender
4. OS update requests get scheduled ([5])
5. Configuration update requests get scheduled

### Key Principles

- Idempotency
- Traceability
- Staged roll outs
- From main branch and upwards no changes
- Proxy between management server and fleet

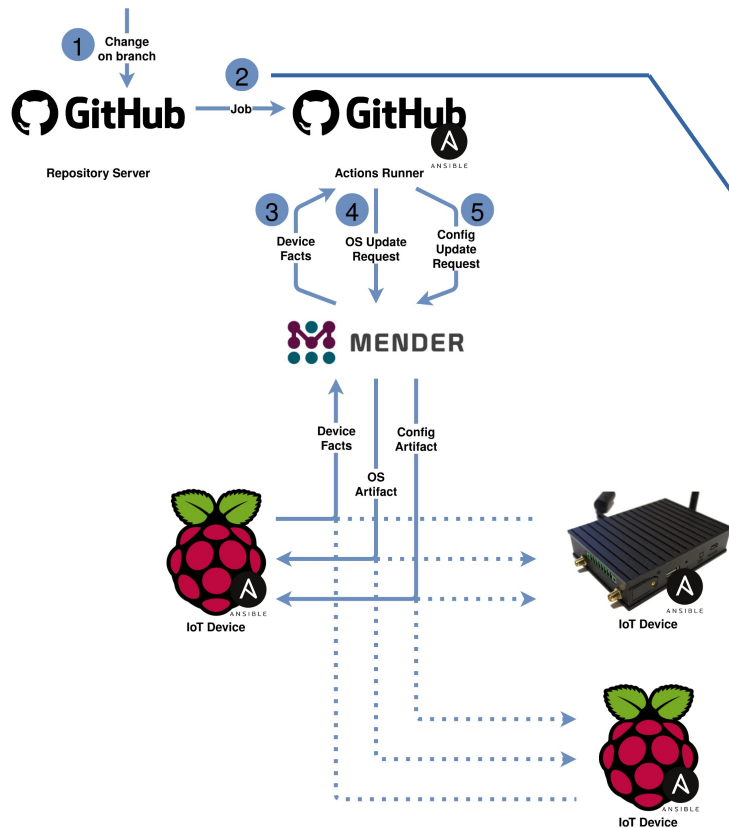
# GitOps

Already familiar tools take care of the orchestration

## Workflow

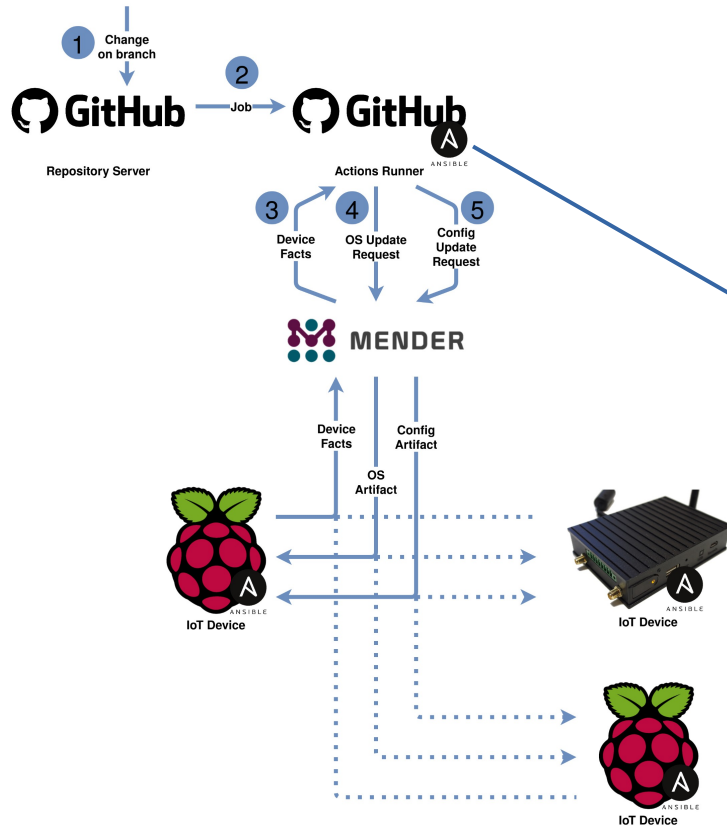
1. A branch gets modified:  
develop/feature branch: commit  
main/canary/production branch: merge
2. GitHub dispatches a job to a runner ([1])  
and the runner clones the fleet repository ([2], [3], [4])

```
1 name: update fleet
2 on:
3   push:
4     workflow_dispatch:
5
6 jobs:
7   build:
8     runs-on: ubuntu-20.04
9     steps:
10      - name: Check out the fleet management playbook
11        uses: actions/checkout@v3
12      - name: Install jmespath into venv of ansible-core
13        run: |
14          source /opt/pipx/venvs/ansible-core/bin/activate
15          python3 -m pip install jmespath
16      - name: Run the fleet management playbook
17        uses: dawidd6/action-ansible-playbook@v2
18        with:
19          playbook: manage-fleet.yml
20          options: --inventory inventory.yml
```



# GitOps

## An Ansible playbook takes care of the fleet

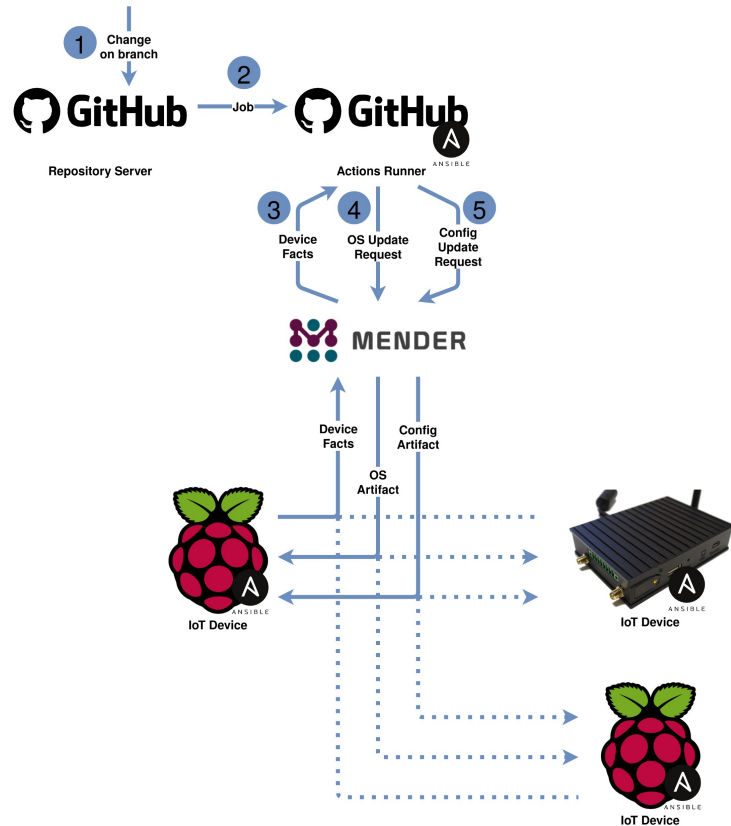


```
1 ---
2 - name: Apply OS and configuration to fleet.
3   hosts: all
4   gather_facts: false
5
6   pre_tasks:
7     - name: Check for minimum required Ansible version (>=2.10).
8       assert:
9         that: "ansible_version.full is version_compare('2.10', '>=')"
10        msg: "Ansible >= 2.10 is required for this playbook."
11        run_once: true
12
13   vars:
14     playbook_mode: "{{ lookup('env', 'PLAYBOOK_MODE') | default('dry-run') }}"
15
16   roles:
17     - role: gather_fleet_facts
18     - role: install_os
19       when: subscribed_branch == applied_branch
20     - role: apply_configuration
21       when: subscribed_branch == applied_branch and configuration.template is defined
```

• Proxy between management server and fleet

# GitOps

## The inventory of the fleet



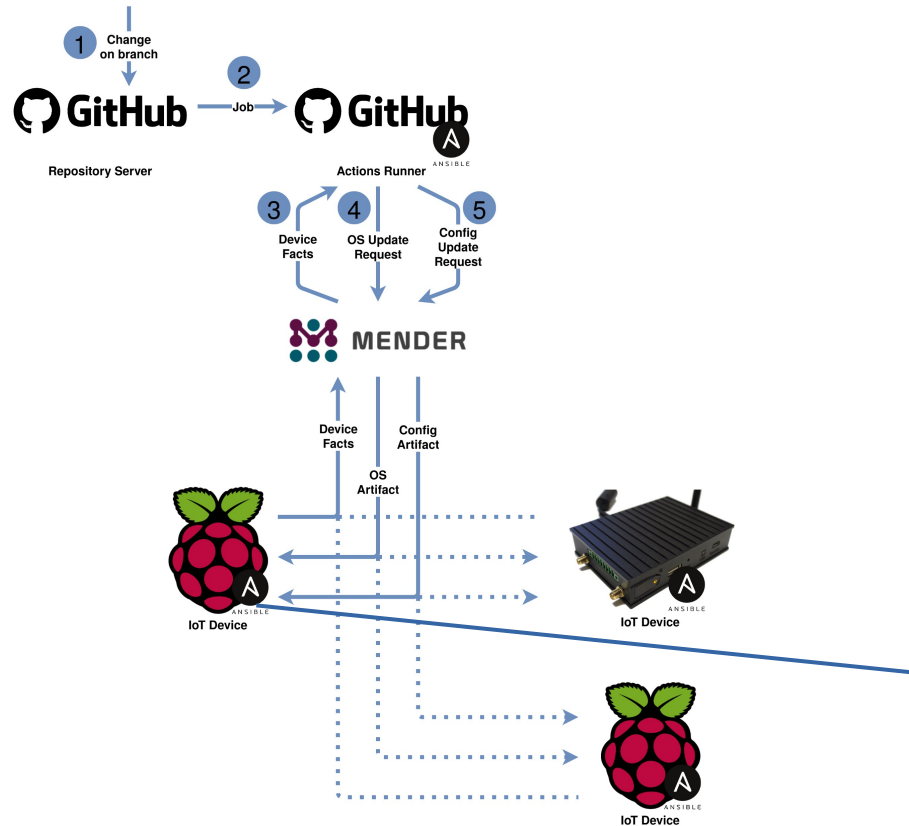
### Workflow

1. A branch gets modified:  
develop/feature branch: commit  
main/canary/production branch: merge
2. GitHub dispatches a job to a runner ([1])  
and the runner clones the fleet repository ([2], [3], [4])  
3. The fleet facts get retrieved from Mender

```
1 all:
2   children:
3     pi4:
4       hosts:
5         b8b311de-000e-4914-9a13-1d7e2e23bc5d: # GitHub runner
6         3fb4632b-96b9-475d-ac89-02255bd15b6f:
7     pi3:
8       hosts:
9         50a28c2e-3ee8-4559-a5b9-3ce47c881c5d:
10        f4580afc-7195-4c8b-b35a-e0248e6bd894:
11     pi2:
12       hosts:
13         048312b5-0456-47a7-9e83-b636f4c0a689:
14     iot_gate_imx8:
15       hosts:
```

# GitOps

## An individual device configuration



### Workflow

1. A branch gets modified:  
develop/feature branch: commit  
main/canary/production branch: merge
2. GitHub dispatches a job to a runner ([1])  
and the runner clones the fleet repository ([2], [3], [4])
3. The fleet facts get retrieved from Mender
4. OS update requests get scheduled ([5])
5. Configuration update requests get scheduled

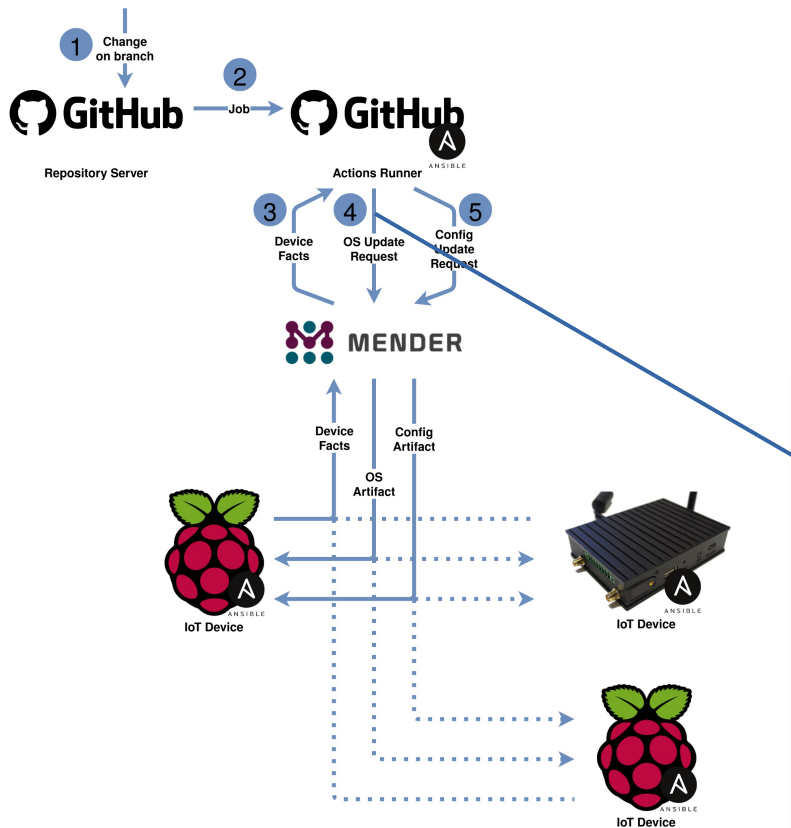
```
1 ---
2 subscribed_branch: main
3
4 configuration:
5   template: kiosk.json
6   parameters:
7     kiosk_url: https://www.get-edl.io
```

# GitOps

## Eventually an OS update will get dispatched

### Workflow

1. A branch gets modified:  
develop/feature branch: commit  
main/canary/production branch: merge
2. GitHub dispatches a job to a runner ([1])  
and the runner clones the fleet repository ([2], [3], [4])
3. The fleet facts get retrieved from Mender
4. OS update requests get scheduled ([5])



```
1 ---
2 mender_server: "https://hosted.mender.io"
3 subscribed_branch: production
4
5 os_image:
6   - device_type: pi2-armhf
7     image_name: 2022-07-08-1050-pi2-bullseye-armhf
8   - device_type: pi3-arm64
9     image_name: 2022-07-08-0859-pi3-bullseye-arm64-gitops
10  - device_type: pi4-v3-arm64
11    image_name: 2022-07-08-0958-pi4-bullseye-arm64-gitops
12  - device_type: var-som-mx8m-nano-arm64-v2
13    image_name: 2022-07-08-1129-var-som-mx8m-nano-bullseye-arm64
```

# GitOps

## Some remarks

- The important *monitoring* aspect is out of scope of this presentation!
- On a large fleet the *inventory* and the *individual device configurations* would be offloaded to a separate tool/database.

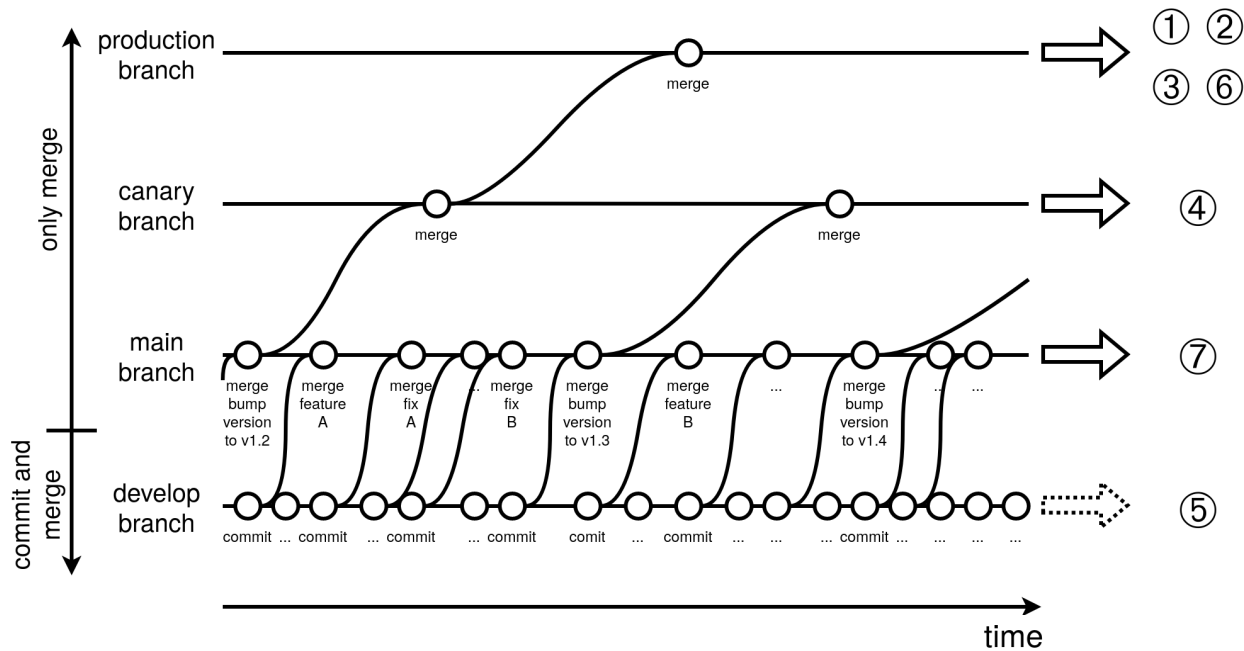
```
1  all:
2    children:
3      pi4:
4        hosts:
5          b8b311de-000e-4914-9a13-1d7e2e23bc5d: # GitHub runner
6          3fb4632b-96b9-475d-ac89-02255bd15b6f:
7      pi3:
8        hosts:
9          50a28c2e-3ee8-4559-a5b9-3ce47c881c5d:
10         f4580afc-7195-4c8b-b35a-e0248e6bd894:
11      pi2:
12        hosts:
13          048312b5-0456-47a7-9e83-b636f4c0a689:
14      iot_gate_imx8:
15        hosts:
16          5ef8c955-4f87-4243-adcd-160f70c3c45e:
17      var_som_mx8m_nano:
18        hosts:
19          ed531b64-5108-4f1d-9879-f39f56054078:
```

```
1  ---
2  subscribed_branch: main
3
4  configuration:
5    template: kiosk.json
6    parameters:
7      kiosk_url: https://www.get-edi.io
```

# Conclusion

# GitOps for Fleet Management

## Key benefits I



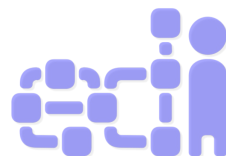
- Everybody is working on the same git repository/talking the same language
- Full traceability
- No changes introduced beyond the main branch – just merges
- Very high level of automation
- Staged roll outs
- Almost no room for human errors

# GitOps for Fleet Management

## Key benefits II



**GitHub**



**debian**

- Powerful toolbox
- Suitable for a huge fleet
- Components are proven in use
- Components are exchangeable
- Fun to work with

# Git Repositories

## CI orchestration

[edi-ci/edi-ci-public](#)

## OS Setup

[edi-pi](#)

[edi-var](#)

[edi-cl](#)

## Continuous Integration

Build an OS image for an IoT device, dispatch it to a device and test it

## Playbooks/Roles

[kiosk-playbook](#)

[ansible-kiosk](#)

[edi-gh-actions-runner-playbook](#)

[ansible-github\\_actions\\_runner](#)

[edi\\_installer](#)

## Device Management

Adjust an IoT device for an individual use case

## CD Orchestration

[edi-cd](#)

## Continuous Delivery

Keep an entire IoT fleet up to date using git

# Links

- [Embedded Meets GitOps](#)
- [Managing an IoT Fleet with GitOps](#)
- [Building and Testing OS Images with GitHub Actions](#)
- [Surprisingly Easy IoT Device Management](#)

# Q&A